

CIS

NCRS – Reverse Articulated Conveyor

For robot placement – stepping mode, part cooling during conveying



Characteristics

Type code	NCRS
Layout	Descending from the upper section (reverse curve)
Mobility	On wheels or on a fixed support
Control	Stepping – robot / manipulator synchronisation
Belt surface	PU supergrip (mandatory)
Optional	A protective cage is recommended at the drop-off point
Sectors	Plastics processing, recycling
Manufacturing	Custom-sized, to customer specification

Typical applications

- ▶ Robot- / manipulator-controlled injection moulding cells – part discharge
- ▶ Cooling finished parts during conveying (supergrip belt)
- ▶ Any application where the conveyor and the robot operate in synchronisation

Why choose it?

- ✓ Stepping mode: can be synchronised with any robot controller
- ✓ PU supergrip: parts do not slip and cool down during conveying
- ✓ Reverse-curve design: parts are placed gently onto the belt
- ✓ Can be retrofitted into existing robot cells

Cyber in Systems Kft.

Exclusive DMD representative
4183 Kaba, Baross Gábor utca 46.

info@cyberin.hu | www.cyberin.hu

Quotation for custom sizes – based on a machine drawing or photo

Lead time: 4–8 weeks