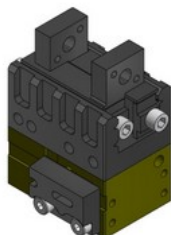
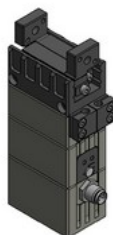


**Parallel Gripper
easy**



**Parallel Gripper
Schunk**



**Parallel Gripper
electric**



**64.0 - Parallel
Gripper Accesories**

Product description

AGS parallel mechanical grippers feature pneumatic drive and interchangeable gripper fingers. They are ideal specifically for applications where vacuum gripping is unreliable: rubber seals, flexible parts, porous or irregularly shaped components. The fingers can be adapted to the workpiece geometry; a cobot version with low force and collision safety is also available.

Typical applications

- › Removing rubber seals from injection moulding machines
- › Handling flexible parts (bellows, hoses)
- › Irregular shapes where vacuum cannot grip
- › Automated workstations alongside cobots
- › Combined EOAT: suction cup + mechanical gripper

Technical specifications

Feature	Value / description
Direction of movement	Parallel (symmetrical)
Drive	Pneumatic
Gripper fingers	Interchangeable – adaptable to the geometry
Cobot version	Low force, collision safety
Combinability	Combines with suction cups on one frame
Typical load	0,1 – 20 kg